

Wrapping Up

Congratulations! You've completed the **Self Leveling Platform** project using inertial sensors and servo motor control, all implemented within the ChipInventor environment. This project introduced you to:

- I2C communication
- Angle estimation using CORDIC
- Feedback control systems
- Digital signal filtering and PWM generation

Feel free to experiment with different parameters, tuning thresholds, or even changing the level reference. Keep exploring and challenging yourself with new digital design projects in ChipInventor!

Revision #1

Created 28 March 2025 18:24:02 by Caroline

Updated 28 March 2025 18:24:42 by Caroline